Eq. 1 Pivot Arm Toggle Mechanism Calculator				
Input cells shown as blue				
clamping force <i>P</i> =	20.000	lbf <b>∨</b>		
length as indicated / =	3.000	in		
length as indicated $I_1$ =	3.000	in		
radius of pivot hole $r$ =	0.250	in		
vertical distance <i>h</i> =	1.500	in		
coefficient of friction $f_o$ =	0.100	-		
coefficient of friction $f_l$ =	0.100	-		
Eq. 1, Calculated Results				
force applied <u>Q</u> =	42.281	lbf		

Eq. 2, Pivot Arm Toggle Mechanism Calculator				
force applied <u>Q</u> =	42.281	lbf <b>∨</b>		
length as indicated / =	3.000	in		
length as indicated $I_1$ =	3.000	in		
radius of pivot hole $r$ =	0.250	in		
vertical distance <i>h</i> =	1.500	in		
coefficient of friction $f_o$ =	0.100	-		
coefficient of friction $f_I$ =	0.100	-		
Eq. 2, Calculated Results				
clamping force <i>P</i> =	20.000	lbf		

Eq. 3, Pivot Arm Toggle Mechanism Calculator				
clamping force <i>P</i> =	20.000	lbf <b>∨</b>		
length as indicated / =	3.000	in		
length as indicated $I_1$ =	3.000	in		
efficiency coefficient <i>n</i> =	0.970	Ī		
Eq. 3, Calculated Results				
force applied <u>Q</u> =	41.237	lbf		

Eq. 4, Pivot Arm Toggle Mechanism Calculator				
force applied <u>Q</u> =	41.237	lbf <b>∨</b>		
length as indicated / =	3.000	in		
length as indicated $I_1$ =	3.000	in		
efficiency coefficient <i>n</i> =	0.970	-		
Eq. 4, Calculated Results				
clamping force <i>P</i> =	20.000	lbf		